

Robô com interface Wii

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0 planejamento

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Sinal Bluetooth



Informação



Ligar os motores de acordo com o sinal

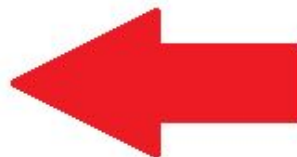


DO YOU KNOW DA WAE?

GOTTA GO FAST



ZUUUUUUUMMM



Mover o tank

0 projeto final

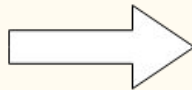
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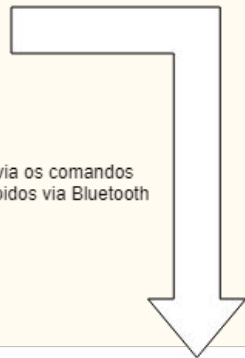
Envia os comandos
inseridos via bluetooth



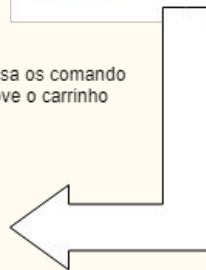
Processa os comandos
recebidos e os transmite via USB



Envia os comandos
recebidos via Bluetooth

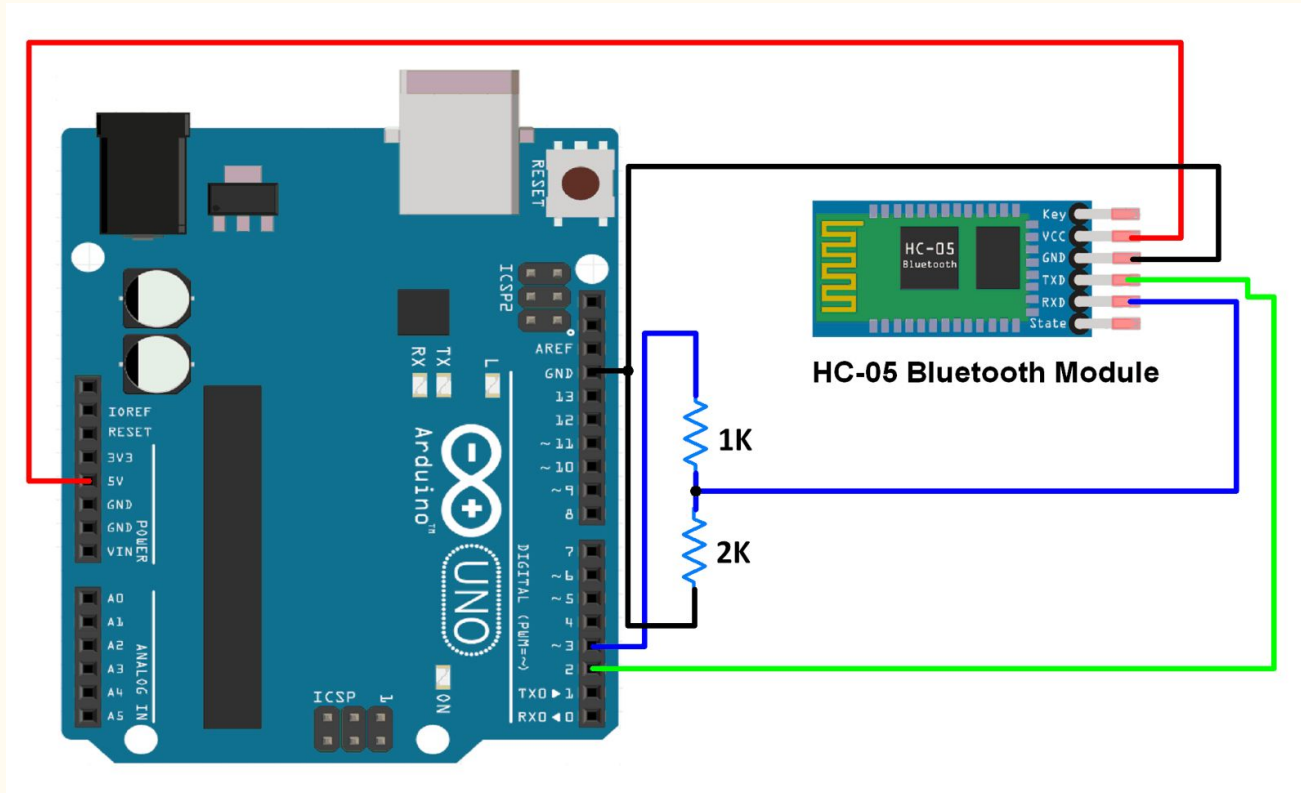


Processa os comando
e move o carrinho

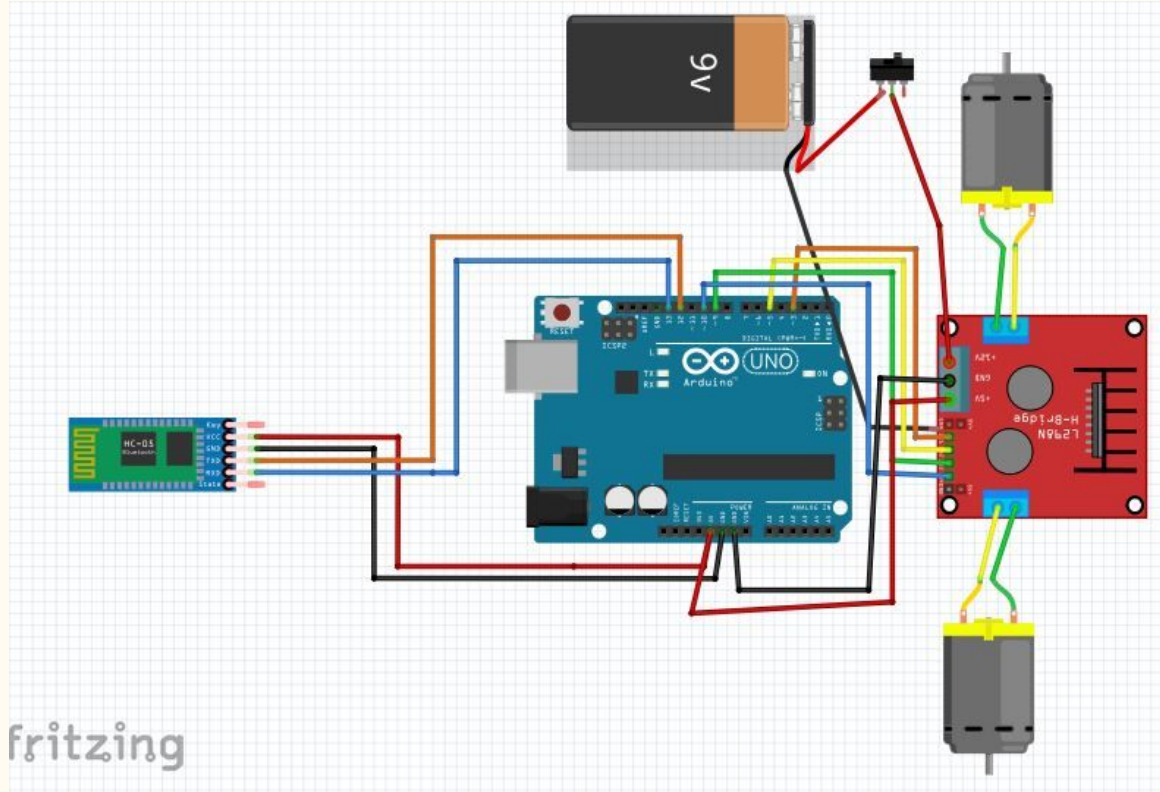


Hardware

Parte 1 - Controlador



Parte 2 - Carrinho



Software

Conclusão



